

DISTRIBUTIVE PROPERTY

To use the distributive property we distribute what is on the outside of the parentheses to the variables and constants on the inside of the parentheses using multiplication.

$$\begin{array}{l} 4(7s + 10) \\ 4 \cdot 7s \quad 4 \cdot 10 \\ 28s + 40 \\ \Rightarrow 28s + 40 \end{array}$$

$$9(x + 10)$$

$$9x + 90$$

$$8(5m + 8n)$$

$$40m + 64n$$

$$2(s - 6t + 8)$$

$$2s - 12t + 16$$

$$4(s - 10t + 8)$$

$$4s - 40t + 32$$

Distributive Property Guided Notes

Mike Jess



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web coordinates of v the standard coordinates are $v = v_1 e_1 + v_2 e_2$ are the b_1, b_2 are assumed if no other basis is specified this means $v = v_1 b_1 + v_2 b_2$ if b_1, b_2 is a basis of \mathbb{R}^n then the matrix S which contains the vectors b_k as column vectors is called the coordinate change matrix

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web the vector \mathbf{b} is parallel to \mathbf{a} and points in the same direction if $\alpha > 0$ for $\alpha < 0$ the vector \mathbf{b} is parallel to but points in the opposite direction antiparallel if we multiply an arbitrary vector \mathbf{a} by the inverse of its magnitude $1/|\mathbf{a}|$ we obtain a

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web sep 17 2022 consider the matrix transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that assigns to a vector \mathbf{x} the closest vector on horizontal axis as illustrated in figure 2.6.20 this transformation is called the projection onto the horizontal axis

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web and now that we know what \mathbf{d} is we can now solve for \mathbf{a} we can now solve for the transformation matrix with respect to the standard basis so to do that we have to figure out \mathbf{c} and \mathbf{c}^{-1} so remember \mathbf{c} is just the change of basis matrix and all that is is the basis vectors it's just a matrix with the basis vectors in the column

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web a translation by a nonzero vector is not a linear map because linear maps must send the zero vector to the zero vector however translations are very useful in performing coordinate transformations i'll introduce the following terminology for the composite of a linear transformation and a translation definition let \mathbf{a} be a real matrix

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web any vector \mathbf{v} represented in \mathbf{b} can be transformed to a representation in \mathbf{c} as follows under the transformation of basis notice that the superscript on the transformation matrix \mathbf{m} and the subscript on the coordinate vector \mathbf{v} are the same and seemingly cancel leaving the remaining subscript

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