

BANKING AND MANAGEMENT INFORMATION SYSTEM AUTOMATION

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Abstract: An Object Oriented Model for large scale projects is proposed, with a formal framework for inheritance, dynamic classification, object specification decomposition, composition of objects (aggregation) and object single and joint behaviour semantics. The model is based on a full concurrent community of objects. It is advocated that such a model enhances concurrency, improves abstraction, refinement and reusability, explains different forms of inheritance and gives a concise semantic for aggregation and exception handling.

Keywords: Concurrency, Events, Inheritance, Interaction, Invariants, Object, Synchronisation

1. INTRODUCTION

The critical aspects of today Banking Management Information Systems are, among others: time to market (dealing with components' development and re-use), evolution (volatility of business requirements), requirements' conformance (take decisions upon correct information), large-scale and complex systems, parallelism, maintenance, robustness and security. Product distribution, management information systems and decision support systems are typical banking applications facing this problems.

Another problem companies are facing today is that they must have a technology migration path planning from current traditional systems to future open systems. An encapsulation mechanism to hide "legacy systems" is essential to guaranty a smooth transition, coping with the business support extensibility.

This paper introduces a rigorous approach, derived from GNOME (Ehrich *et al.*, 1993; Saake *et al.*, 1993), addressing, among other things, normative and non-

normative behaviour, inheritance and composition and decomposition.

Effort was made to introduce a well defined semantic, in order to fulfil the following desirable characteristics for object-oriented approaches: *method composition and extension, dynamic classification, direct object interaction and event broadcast, behaviour inheritance, compositionality and encapsulation*. Some properties relevant to wider software engineering were also included, namely: the ability to specify concurrent behaviour and properties; the ability to deal with non-normative behaviour (*exception handling*); allowing the systematic refinement of specifications to code, preferably in a compositional manner.

According to these principles, an **Information System** is treated as a *collection of interacting concurrent objects* where the object notion is the unification of the system constituents.

An **object** is an abstraction with a persistent *identity*, a *public interface* defined by the provided services and recognised events (only way to interact with the object, accessing its internal state) and an *internal body*, including

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**Evan L. Russell, Leo H. Chiang, Richard
D. Braatz**

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Application and Theory of Petri Nets 1997 Pierre Azema, Gianfranco Balbo, 1997-06-04 This book constitutes the refereed proceedings of the 18th International Conference on the Application and Theory of Petri Nets ICATPN 97 held in Toulouse France in June 1997 The 22 revised full papers presented in the volume were selected from a total of 61 submissions also included are three invited contributions All relevant topics in the area are addressed Besides a variety of Petri net classes workflow management telecommunication networking constraint satisfaction program semantics concurrency and temporal logic are among the topics addressed *Performance Assessment of Control Loops* Biao Huang, Sirish L. Shah, 2012-12-06 The series *Advances in Industrial Control* aims to report and encourage technology transfer in control engineering The rapid development of control technology has an impact on all areas of the control discipline New theory new controllers actuators sensors new industrial processes computer methods new applications new philosophies new challenges Much of this development work resides in industrial reports feasibility study papers and the reports of advanced collaborative projects The series offers an opportunity for researchers to present an extended exposition of such new work in all aspects of industrial control for wider and rapid dissemination Benchmarking is a technique first applied by Rank Xerox in the late 1970s for business processes As a subject in the commercial arena benchmarking thrives with for example a European Benchmarking Forum It has taken rather longer for benchmarking to make the transfer to the technical domain and even now the subject is making a slow headway A key research step in this direction was taken by Harris 1989 who used minimum variance control as a benchmark for controller loop assessment This contribution opened up the area and a significant specialist literature has now developed Significant support for the methodology was given by Honeywell who have controller assessment routines in their process control applications software therefore it is timely to welcome a first monograph on controller performance assessment by Biao Huang and Sirish Shah to the *Advances in Industrial Control* series **Fault Detection and Diagnosis in Industrial Systems** L.H. Chiang, E.L. Russell, R.D. Braatz, 2012-12-06 Early and accurate fault detection and diagnosis for modern chemical plants can minimise downtime increase the safety of plant operations and reduce manufacturing costs The process monitoring techniques that have been most effective in practice are based on models constructed almost entirely from process data The goal of the book is to present the theoretical background and practical techniques for data driven process monitoring Process monitoring techniques presented include Data driven methods principal component analysis Fisher discriminant analysis partial least squares and canonical variate analysis Analytical Methods parameter estimation observer based methods and parity relations Knowledge based methods causal analysis expert systems and pattern recognition The text demonstrates the application of all of the data driven process monitoring techniques to the Tennessee Eastman plant simulator demonstrating the strengths and weaknesses of each approach in detail This aids the reader in selecting the right method for his process application Plant simulator and homework problems in which students apply the

process monitoring techniques to a non trivial simulated process and can compare their performance with that obtained in the case studies in the text are included A number of additional homework problems encourage the reader to implement and obtain a deeper understanding of the techniques The reader will obtain a background in data driven techniques for fault detection and diagnosis including the ability to implement the techniques and to know how to select the right technique for a particular application

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Control in Robotics and Automation Bijoy K. Ghosh, T. J. Tarn, Ning Xi, 1999-04-09 Microcomputer technology and micromechanical design have contributed to recent rapid advances in Robotics Particular advances have been made in sensor technology that allow robotic systems to gather data and react intelligently in flexible manufacturing systems The analysis and recording of the data are vital to controlling the robot In order to solve problems in control and planning for a Robotic system it is necessary to meet the growing need for the integration of sensors in to the system Control in Robotics and Automation addresses this need This book covers integration planning and control based on prior knowledge and real time sensory information A new task oriented approach to sensing planning and control introduces an event based method for system design together with task planning and three dimensional modeling in the execution of remote operations Typical remote systems are teleoperated and provide work efficiencies that are on the order of ten times slower than what is directly achievable by humans Consequently the effective integration of automation into teleoperated remote systems offers potential to improve remote system work efficiency The authors introduce visually guided control systems and study the role of computer vision in autonomously guiding a robot system Sensor Based Planning and Control in an Event Based Approach Visually Guided Sensing and Control Multiple Sensor Fusion in Planning and Control

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