



Adaptive Dual Control

Joacim Rocklöv



Adaptive Dual Control:

Adaptive Dual Control Nikolai Michailovich Filatov, Heinz Unbehauen, 2004-04-20 This monograph demonstrates how the performance of various well known adaptive controllers can be improved significantly using the dual effect The modifications to incorporate dual control are realized separately and independently of the main adaptive controller without complicating the algorithms A new bicriterial approach for dual control is developed and applied to various types of popular linear and nonlinear adaptive controllers Practical applications of the designed controllers to several real time problems are presented This monograph is the first book providing a complete exposition on the dual control problem from the inception in the early 1960s to the present state of the art aiming at students and researchers in adaptive control as well as design engineers in industry

Adaptive Dual Control Nikolai Michailovich Filatov, Heinz Unbehauen, 2014-03-12 This monograph demonstrates how the performance of various well known adaptive controllers can be improved significantly using the dual effect The modifications to incorporate dual control are realized separately and independently of the main adaptive controller without complicating the algorithms A new bicriterial approach for dual control is developed and applied to various types of popular linear and nonlinear adaptive controllers Practical applications of the designed controllers to several real time problems are presented This monograph is the first book providing a complete exposition on the dual control problem from the inception in the early 1960s to the present state of the art aiming at students and researchers in adaptive control as well as design engineers in industry

Stochastic adaptive control for a class of dual control problems Yungsun Hahn, 1990

Adaptive Dual Control for Industrial Processes Y.K.L.M. Prevo, 2013

Adaptive Control Karl J. Åström, Björn Wittenmark, 2013-04-26 Suitable for advanced undergraduates and graduate students this overview introduces theoretical and practical aspects of adaptive control with emphasis on deterministic and stochastic viewpoints 1995 edition

Dual Adaptive Control Based Upon Sensitivity Functions J. A. Molusis, P. Mookerjee, Y. Bar-Shalom, CONNECTICUT UNIV STORRS DEPT OF ELECTRICAL ENGINEERING AND COMPUTER SCIENCE., 1984 A new adaptive dual control solution is presented for the control of a class of multivariable input output systems Both rapidly varying random parameters and constant but unknown parameters are included The new controller modifies the cautious control design by numerator and denominator correction terms This controller is shown to depend upon sensitivity functions of the expected future cost A scalar example is presented to provide insight into the properties of the new dual controller Monte Carlo simulations are performed which show improvement over the cautious controller and the Linear Feedback Dual Controller of two previous publications Author

Dual Adaptive Control: Design Principles and Applications, 1988

Dual Adaptive Control National Aeronautics and Space Adm Nasa, 2018-11-13 The design of an actively adaptive dual controller based on an approximation of the stochastic dynamic programming equation for a multi step horizon is presented A dual controller that can enhance identification of the system while controlling it at the same time is derived for multi dimensional problems This

dual controller uses sensitivity functions of the expected future cost with respect to the parameter uncertainties A passively adaptive cautious controller and the actively adaptive dual controller are examined In many instances the cautious controller is seen to turn off while the latter avoids the turn off of the control and the slow convergence of the parameter estimates characteristic of the cautious controller The algorithms have been applied to a multi variable static model which represents a simplified linear version of the relationship between the vibration output and the higher harmonic control input for a helicopter Monte Carlo comparisons based on parametric and nonparametric statistical analysis indicate the superiority of the dual controller over the baseline controller Mookerjee Purusottam Unspecified Center ADAPTIVE CONTROL DESIGN ANALYSIS HARMONIC CONTROL HELICOPTERS VIBRATION DAMPING DIMENSIONS DYNAMIC PROGRAMMING ESTIMATES MONTE CARLO METHOD PARAMETER IDENTIFICATION STATIC MODELS STATISTICAL ANALYSIS STOCHASTIC PROCESSES **CONTROL SYSTEMS, ROBOTICS AND AUTOMATION - Volume X** Heinz D.

Unbehauen,2009-10-11 This Encyclopedia of Control Systems Robotics and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS which is an integrated compendium of twenty one Encyclopedias This 22 volume set contains 240 chapters each of size 5000 30000 words with perspectives applications and extensive illustrations It is the only publication of its kind carrying state of the art knowledge in the fields of Control Systems Robotics and Automation and is aimed by virtue of the several applications at the following five major target audiences University and College Students Educators Professional Practitioners Research Personnel and Policy Analysts Managers and Decision Makers and NGOs *Trends in Advanced Intelligent Control, Optimization and Automation* Wojciech Mitkowski,Janusz Kacprzyk,Krzysztof Oprzędkiewicz,Paweł Skruch,2017-06-06 This volume contains the proceedings of the KKA 2017 the 19th Polish Control Conference organized by the Department of Automatics and Biomedical Engineering AGH University of Science and Technology in Krak w Poland on June 18 21 2017 under the auspices of the Committee on Automatic Control and Robotics of the Polish Academy of Sciences and the Commission for Engineering Sciences of the Polish Academy of Arts and Sciences Part 1 deals with general issues of modeling and control notably flow modeling and control sliding mode predictive dual etc control In turn Part 2 focuses on optimization estimation and prediction for control Part 3 is concerned with autonomous vehicles while Part 4 addresses applications Part 5 discusses computer methods in control and Part 6 examines fractional order calculus in the modeling and control of dynamic systems Part 7 focuses on modern robotics Part 8 deals with modeling and identification while Part 9 deals with problems related to security fault detection and diagnostics Part 10 explores intelligent systems in automatic control and Part 11 discusses the use of control tools and techniques in biomedical engineering Lastly Part 12 considers engineering education and teaching with regard to automatic control and robotics

Optimization and Control for Systems in the Big-Data Era Tsan-Ming Choi,Jianjun Gao,James H. Lambert,Chi-Kong Ng,Jun Wang,2017-05-04 This book focuses on optimal control and systems engineering in the big data era It examines the

scientific innovations in optimization control and resilience management that can be applied to further success In both business operations and engineering applications there are huge amounts of data that can overwhelm computing resources of large scale systems This big data provides new opportunities to improve decision making and addresses risk for individuals as well in organizations While utilizing data smartly can enhance decision making how to use and incorporate data into the decision making framework remains a challenging topic Ultimately the chapters in this book present new models and frameworks to help overcome this obstacle Optimization and Control for Systems in the Big Data Era Theory and Applications is divided into five parts Part I offers reviews on optimization and control theories and Part II examines the optimization and control applications Part III provides novel insights and new findings in the area of financial optimization analysis The chapters in Part IV deal with operations analysis covering flow shop operations and quick response systems The book concludes with final remarks and a look to the future of big data related optimization and control problems

Essential C# fast Ian Chivers,2003-04-08 A quick and practical introduction to the C programming language The text includes complete programming examples that highlight the core features of this language In this book you will learn about Using C with a traditional compile run cycle using C within the Developer Studio environment different data types supported in C control structures and input and output i o in C key features of C and their relationship to C C Java and other programming languages

Stochastic Control N.K. Sinha,L.A. Telksnys,2014-05-23 Stochastic control the control of random processes has become increasingly more important to the systems analyst and engineer The Second IFAC Symposium on Stochastic Control represents current thinking on all aspects of stochastic control both theoretical and practical and as such represents a further advance in the understanding of such systems

Adaptive Estimation and Dual Control with Applications to Defense Communications System Controls Edison Tse,Robert E. Larson,Yaakov Bar-Shalom,SYSTEMS CONTROL INC PALO ALTO CALIF.,1975 Adaptive linear filters with the capability of tracking nonstationary noise statistics have been developed These algorithms offer potentially improved solution methods for problems with significant nonlinearities in the system and measurement equations high dimensional problems and problems in which the noise statistics are not exactly known The application to a precision pointing and tracking problem for a telescope has been carried out to illustrate the potential benefits of an adaptive estimation algorithm The simulation results show a sizable reduction in the pointing error compared to a non adaptive filter The previously developed dual control algorithm has been successfully applied to a missile guidance problem Some further theoretical work on dual control has also been performed It has been shown that the certainty equivalence property holds for a general class of problems if and only if the control has no dual effect

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An Adaptive Dual-mode Controller George W. Muller,1960

Advances and Innovations in Systems, Computing Sciences

and Software Engineering Khaled Elleithy, 2007-08-28 Advances and Innovations in Systems Computing Sciences and Software Engineering includes a set of rigorously reviewed world class manuscripts addressing and detailing state of the art research projects in the areas of Computing Sciences Software Engineering and Systems Advances and Innovations in Systems Computing Sciences and Software Engineering includes selected papers from the conference proceedings of the International Conference on Systems Computing Sciences and Software Engineering SCSS 2006 which was part of the International Joint Conferences on Computer Information and Systems Sciences and Engineering CISSE 2006 All aspects of the conference were managed on line not only the reviewing submissions and registration processes but also the actual conference Conference participants authors presenters and attendees only needed an internet connection and sound available on their computers in order to be able to contribute and participate in this international ground breaking conference The on line structure of this high quality event allowed academic professionals and industry participants to contribute work and attend world class technical presentations based on rigorously refereed submissions live without the need for investing significant travel funds or time out of the office Suffice to say that CISSE received submissions from more than 70 countries for whose researchers this opportunity presented a much more affordable dynamic and well planned event to attend and submit their work to versus a classic on the ground conference The CISSE conference audio room provided superb audio even over low speed internet connections the ability to display PowerPoint presentations and cross platform compatibility the conferencing software runs on Windows Mac and any other operating system that supports Java In addition the conferencing system allowed for an unlimited number of participants which in turn granted CISSE the opportunity to allow all participants to attend all presentations as opposed to limiting the number of available seats for each session

Dual Adaptive Control Purusottam Mookerjee, 1986

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web removing a light bulb turn the refrigerator to off depending on your model either turn the freezer control to the word off or press the minus sign touch pads repeatedly until a dash appears in both the freezer and refrigerator displays as shown disconnect the refrigerator from the electrical source when you

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web reinstall the wiring clip the bracket wire using a 1 4 hexagonal head socket wrench 7 connect the wiring plugs from the bracket wire 8 lift the refrigerator door enough to insert the door into the bottom hinge pin see graphic 7 important 1

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